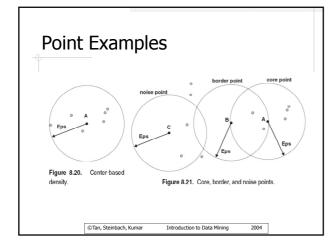


DBSCAN

Density-Based Spatial Clustering of Applications with Noise

Classification of Points

- Given a radius ϵ and the minimum number of points MinPts within a radius of ϵ (ϵ -neighborhood)
 - Core point
 - Points in its ε-neighborhood ≥ MinPts
 - Border points
 - \bullet Within the $\epsilon\text{-neighborhood}$ of a core point
 - Noise points



The DBSCAN Algorithm

- Label all points as core, border, or noise
- Remove all noise points
- Put an edge between all core points that are within ε of each other
- Make each connected group of core points a cluster
- Assign border points to one of the clusters of their associated core points

