

CS422 Principles of Database Systems

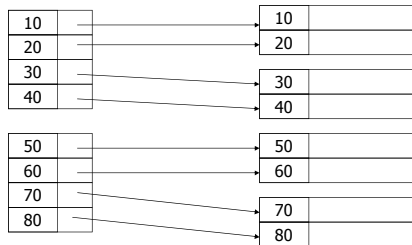
Indexes

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Indexes

- ◆ Auxiliary structures that speed up operations that are not supported efficiently by the basic file organization

A Simple Index Example



Index blocks

Data blocks

About Indexes

- ◆ Index entry
 - <key, rid>
 - <key, list of rid>
 - Data record
- ◆ The majority of database indexes are designed to reduce *disk access*

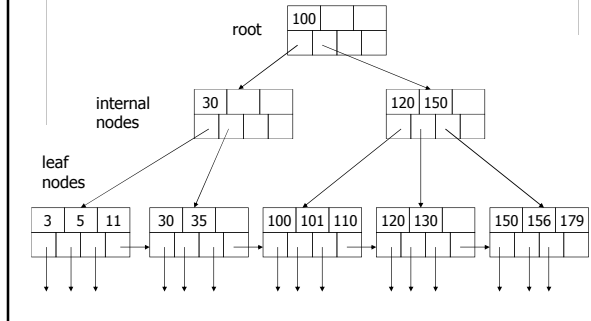
Organization of Index Entries

- ◆ Tree-structured
 - B-tree, R-tree, Quad-tree, kd-tree, ...
- ◆ Hash-based
 - Static, dynamic
- ◆ Other
 - Bitmap, VA-file, ...

From BST to BBST to B

- ◆ Binary Search Tree
 - Worst case??
- ◆ Balance Binary Search Tree
 - E.g. AVL, Red-Black
- ◆ B-tree
 - Why not use BBST in databases??

B-tree (B⁺-tree) Example



B-tree Properties

- ◆ Each node occupies one block
- ◆ Order n
 - n keys, $n+1$ pointers
- ◆ Nodes (except root) must be at least half full
 - Internal node: $\lceil (n+1)/2 \rceil$ pointers
 - Leaf node: $\lfloor (n+1)/2 \rfloor$ pointers
- ◆ All leaf nodes are on the same level

B-tree Operations

- ◆ Search
- ◆ Insert
- ◆ Delete

B-tree Insert

- ◆ Find the appropriate leaf
- ◆ Insert into the leaf
 - there's room \rightarrow we're done
 - no room
 - split leaf node into two
 - insert a new $\langle \text{key}, \text{pointer} \rangle$ pair into leaf's parent node
- ◆ *Recursively apply previous step if necessary*
 - A split of current ROOT leads to a new ROOT

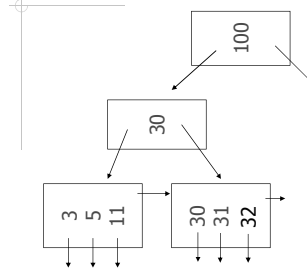
B-tree Insert Examples

- ◆ (a) simple case
 - space available in leaf
- ◆ (b) leaf overflow
- ◆ (c) non-leaf overflow
- ◆ (d) new root

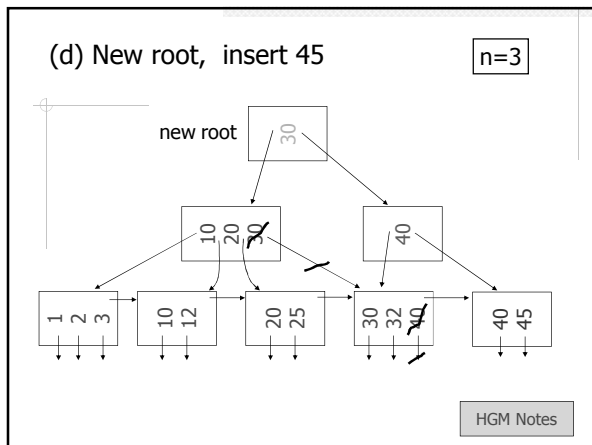
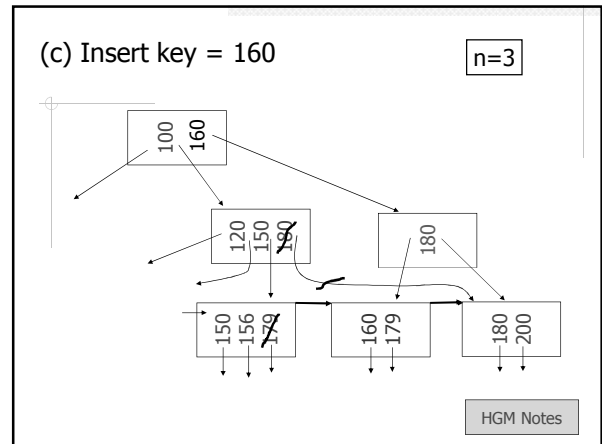
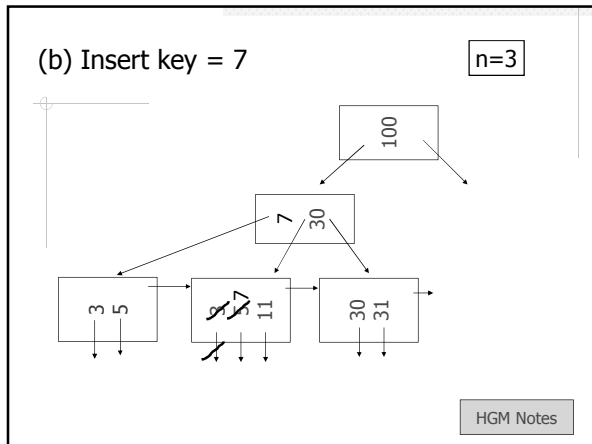
HGM Notes

(a) Insert key = 32

$n=3$



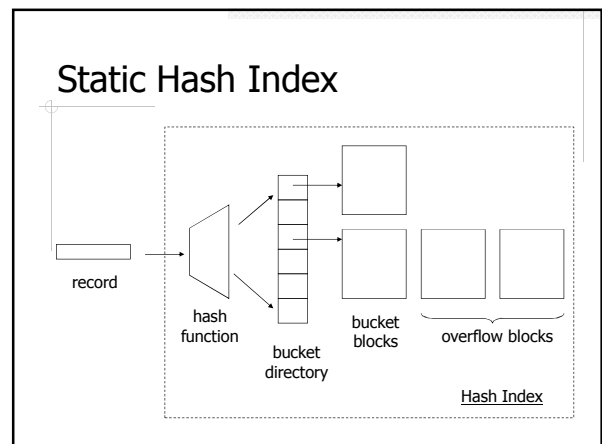
HGM Notes



- ### B-tree Delete
- ◆ Find the appropriate leaf
 - ◆ Delete from the leaf
 - still at least half full → we're done
 - below half full – coalescing
 - borrow a <key,pointer> from one sibling node, *or*
 - merge with a sibling node, and delete from a parent node
 - ◆ Recursively apply previous step if necessary

B-tree Delete in Practice

- ◆ Coalescing is usually not implemented because it's too hard and not worth it



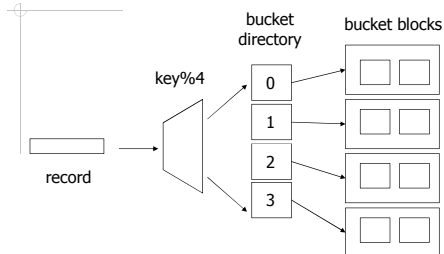
Hash Function

- ◆ A commonly used hash function: $K \% B$
 - K is the key value
 - B is the number of buckets

Static Hash Index Example ...

- ◆ 4 buckets
- ◆ Hash function: $key \% 4$
- ◆ 2 index entries per bucket block

... Static Hash Index Example



- ◆ Insert the records with the following keys: 4, 3, 7, 17, 22, 10, 25, 33

Dynamic Hashing

- ◆ Problem of static hashing??
- ◆ Dynamic hashing
 - Extendable Hash Index

Extendable Hash Index ...

- ◆ Maximum 2^M buckets
 - M is maximum depth of index
- ◆ Multiple buckets can share the same block
- ◆ Inserting a new entry to a block that is already full would cause the block to split

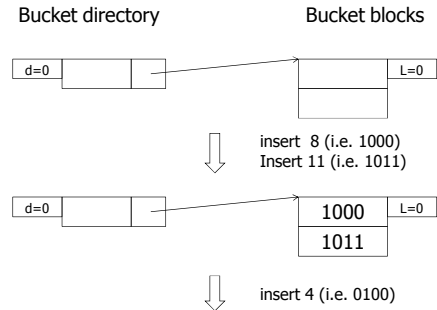
... Extendable Hash Index

- ◆ Each block has a local depth L , which means that the hash values of the records in the block has the same rightmost L bit
- ◆ The bucket directory keeps a global depth d , which is the highest local depth

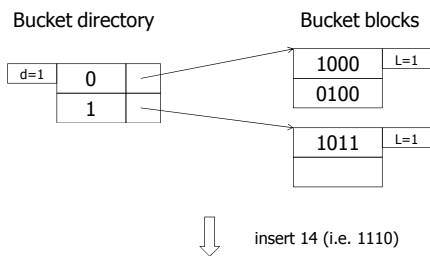
Extendable Hash Index Example

- ◆ $M=4$ (i.e. could have at most 16 buckets)
- ◆ Hash function: $key \% 2^4$
- ◆ 2 index entries per block
- ◆ Insert 8, 11, 4, 14

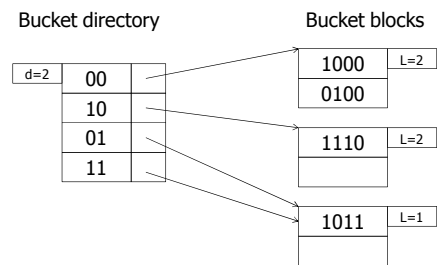
Extendable Hashing (I)



Extendable Hashing (II)



Extendable Hashing (III)



Readings

- ◆ Textbook Chapter 21.1 – 21.4